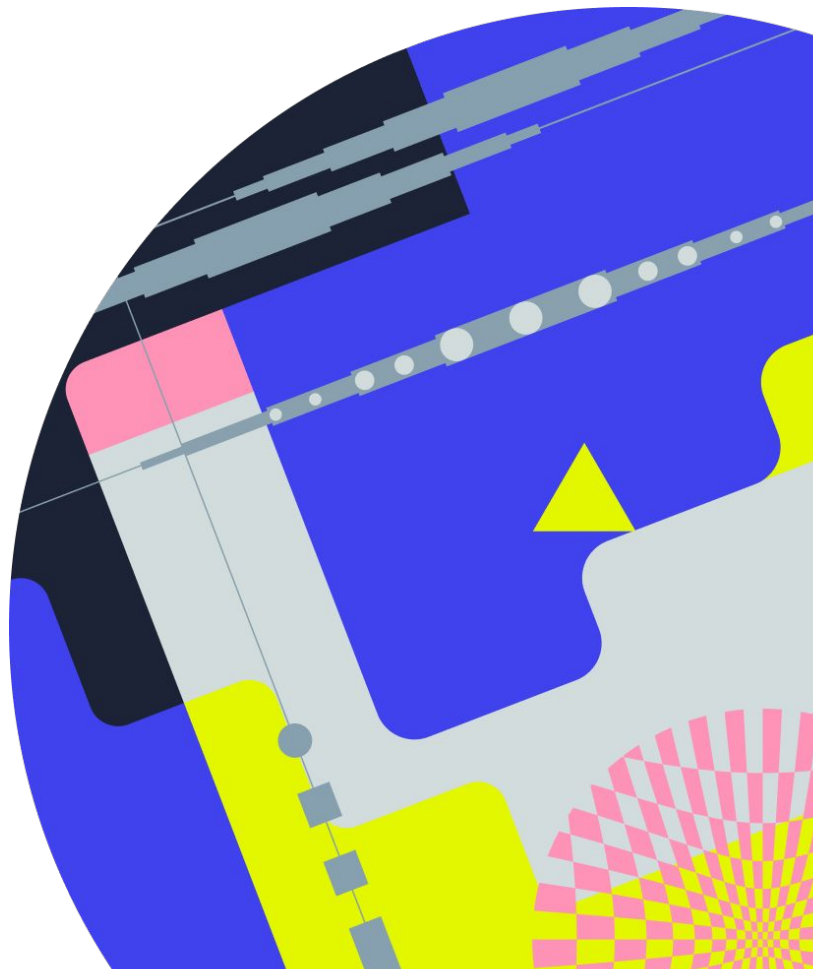


Seminar 2: Early Fusion. Video modality

Supplementary slides to [Google Colab notebook](#)

Zinkovich Viktoriia



Recap of previous seminar

1. Deep Fusion

deeply fuses multimodal inputs
within internal layers



1.1. Standard

Cross-Attention (SC-DF)

OpenFlamingo

- perceiver resampler
- cross-attention
- tanh gating



1.2. Custom

Layers (CL-DF)

MoE-LLaVA

- vision encoder MLP
- Mixture-of-Experts layer
- Router



2. Early Fusion

multimodal inputs are fed to the
model rather to its internals



2.1. Non-tokenized

(NT-EF)

2.2. Tokenized

(T-EF)

Questions



Giving **OpenFlamingo** tricky few-shot examples
training dataset = LAION-2B with image-text pairs

An image of $2 \times 2 = 4$

$$2 \times 2 = 4$$

An image of $3 + 3 = 6$

$$3 + 3 = 6$$

An image of

$$1 + 1 = 2$$

An image of $1 + 1 = 2$

$$1 + 1 = 2$$

input images and prompts

output

Questions



Giving **OpenFlamingo** tricky few-shot examples
training dataset = LAION-2B with image-text pairs

An image of $2 \times 2 = 4$

$$2 \times 2 = 4$$

An image of $3 + 3 = 6$

$$3 + 3 = 6$$

What is the color of board?

$$1 + 1 = 2$$

input images and prompts

An image of $2 + 2 = 4$.

An image of $3 + 3 = 6$

$$1 + 1 = 2$$

output

Questions



Giving **OpenFlamingo** tricky few-shot examples
training dataset = LAION-2B with image-text pairs

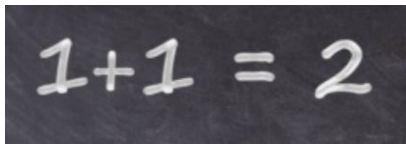
Print equation: $2 \times 2 = 4$

Print equation: $3 + 3 = 6$

Print equation:

$$2 \times 2 = 4$$

$$3 + 3 = 6$$



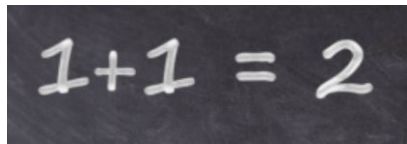
input images and prompts

Print equation $2 + 2 = 4$

Print equation $3 + 3 = 6$

Print equation $2 + 2 = 4$

Print



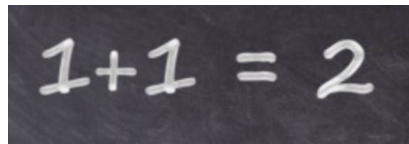
output

Questions



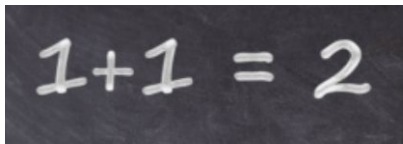
Giving **OpenFlamingo** tricky few-shot examples
training dataset = LAION-2B with image-text pairs

An image of



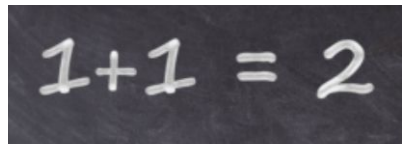
input

An image of a
blackboard with a plus
and minus sign on it.



output

What is on the image?
<|endofchunk|>



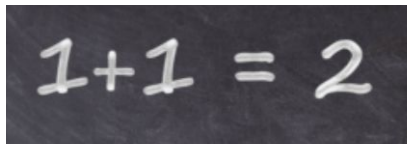
input

Questions



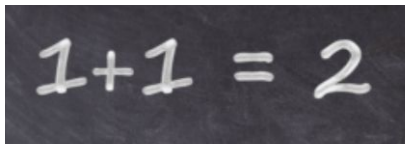
Giving **OpenFlamingo** tricky few-shot examples
training dataset = LAION-2B with image-text pairs

An image of



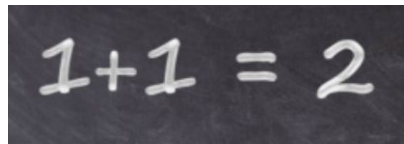
input

An image of a
blackboard with a plus
and minus sign on it.



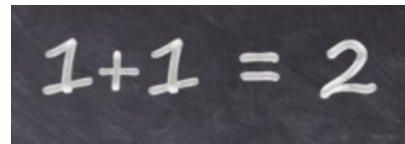
output

What is on the image?
<|endofchunk|>



input

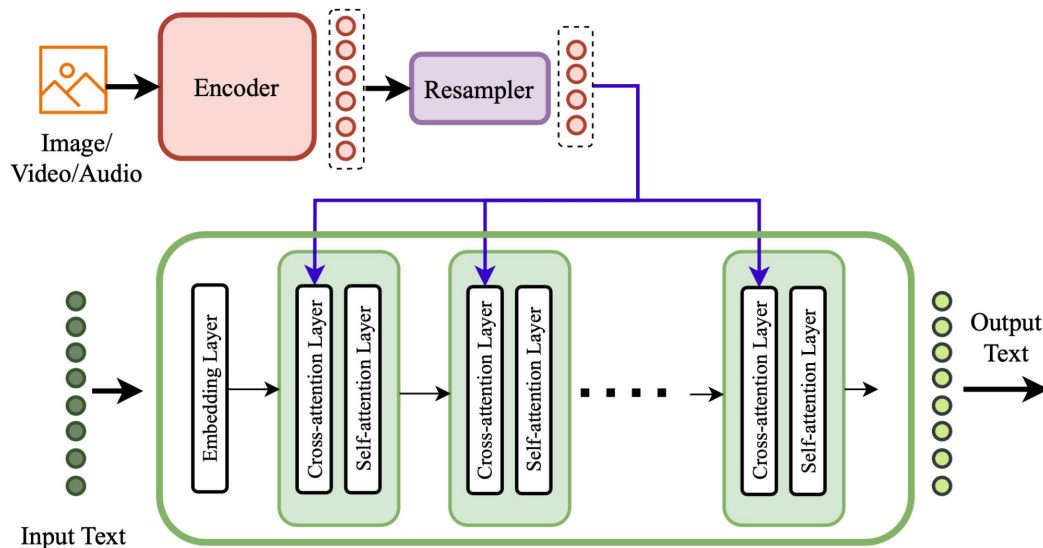
I've been thinking a lot
lately about what it means
to be a "successful"



output

Questions

Cross-attention between **three sequences** (modalities)



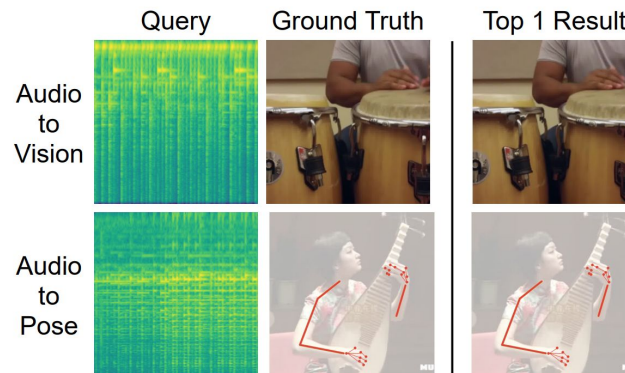
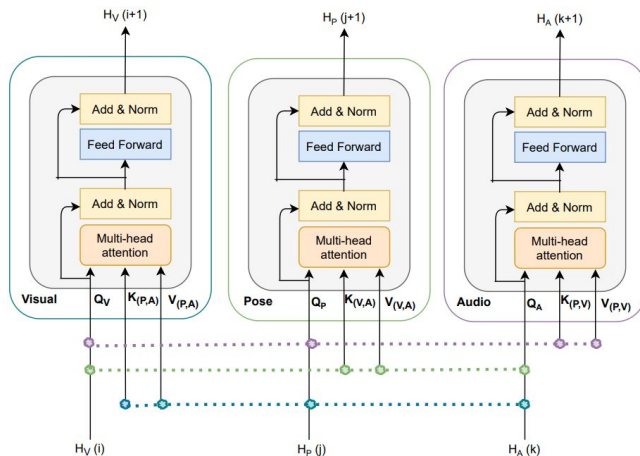
Cross-attention between **two modalities** (text and image) is used in **Deep Fusion**, particularly in cross-attention layers inside LLM

(again: OpenFlamingo)

Questions

Cross-attention between **three sequences** (modalities)

tri-modal co-attention in TriBERT

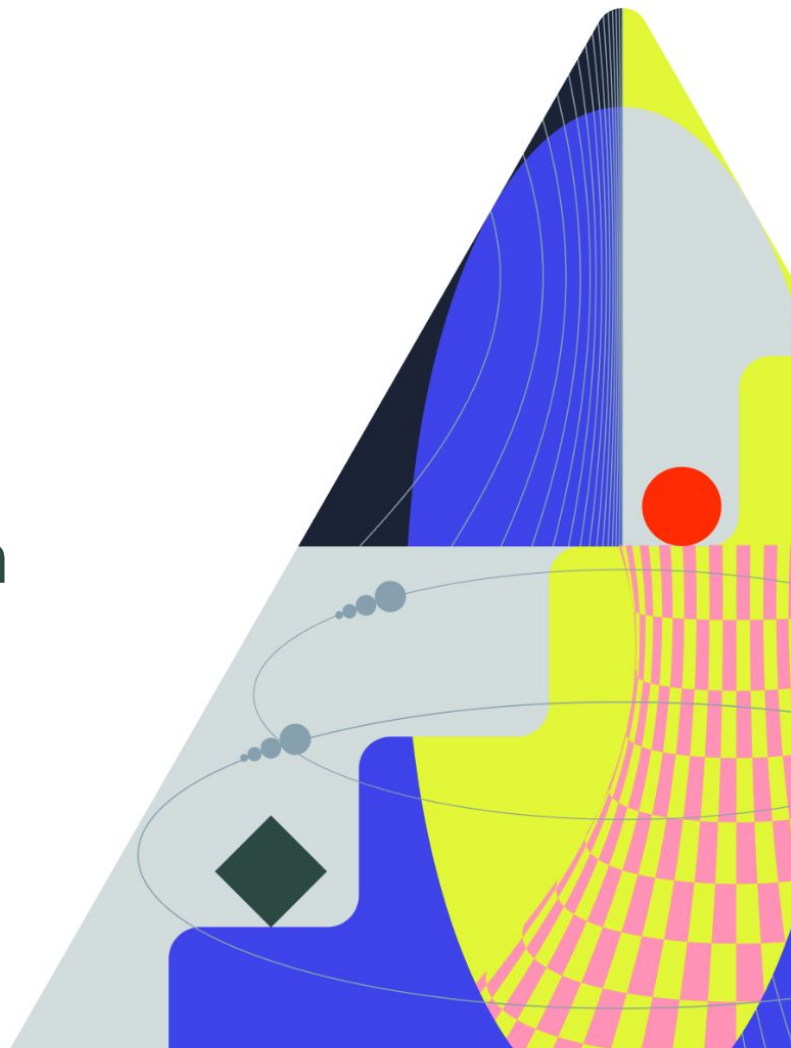


- [1] **TriBERT**: Full-body Human-centric Audio-visual Representation Learning for Visual Sound Separation. **NeurIPS** 2021. [\[link\]](#)
- [2] **TriCAFFNet**: A Tri-Cross-Attention Transformer with a Multi-Feature Fusion Network for Facial Expression Recognition. 2021. [\[link\]](#)

2.1

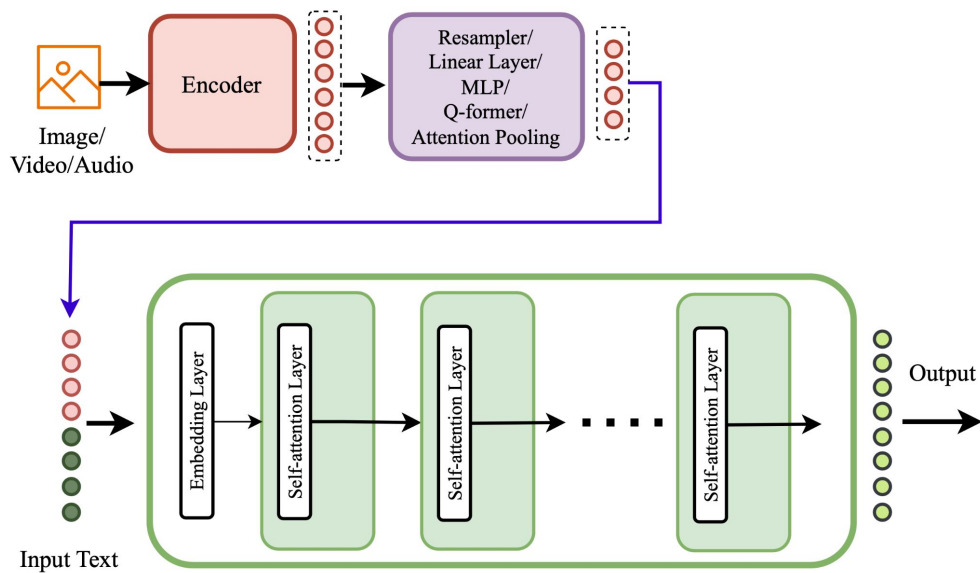
Early Fusion:

Non-Tokenized Early Fusion
(NT-EF)



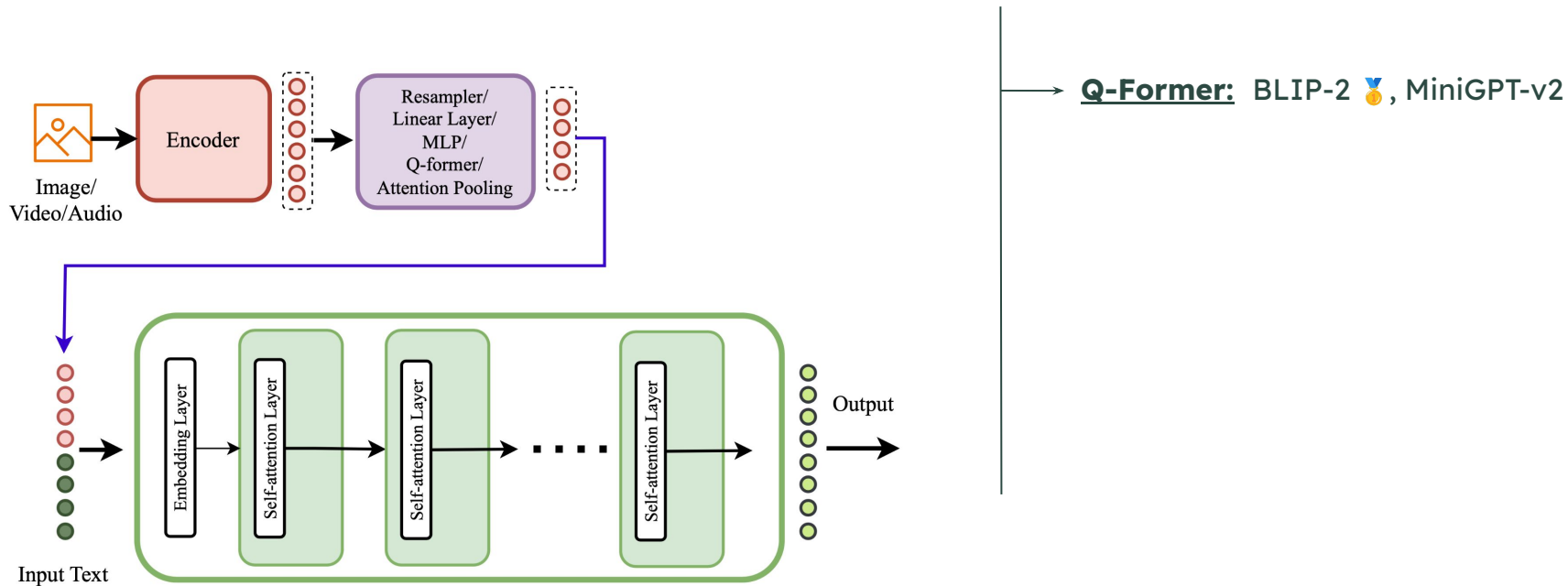
NT-EF: Non-Tokenized

Non-tokenized input modalities are **directly fed to the model** rather than to internal layers



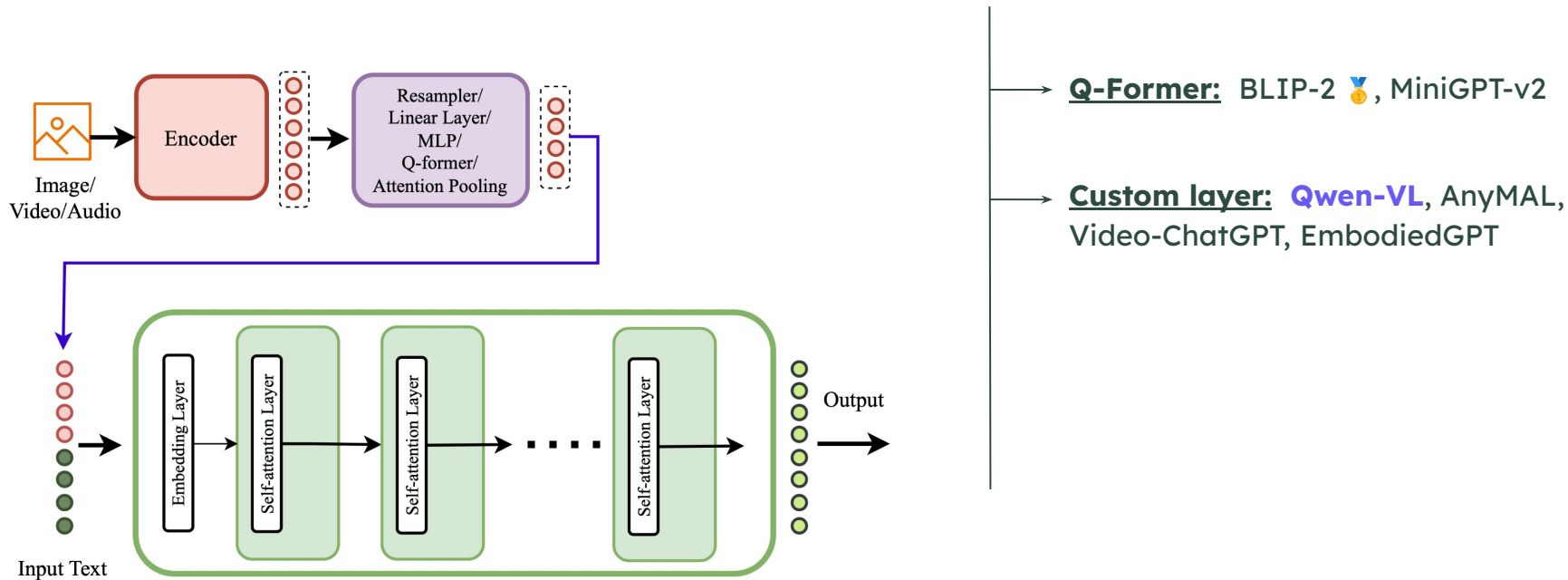
NT-EF: Non-Tokenized

Non-tokenized input modalities are **directly fed to the model** rather than to internal layers



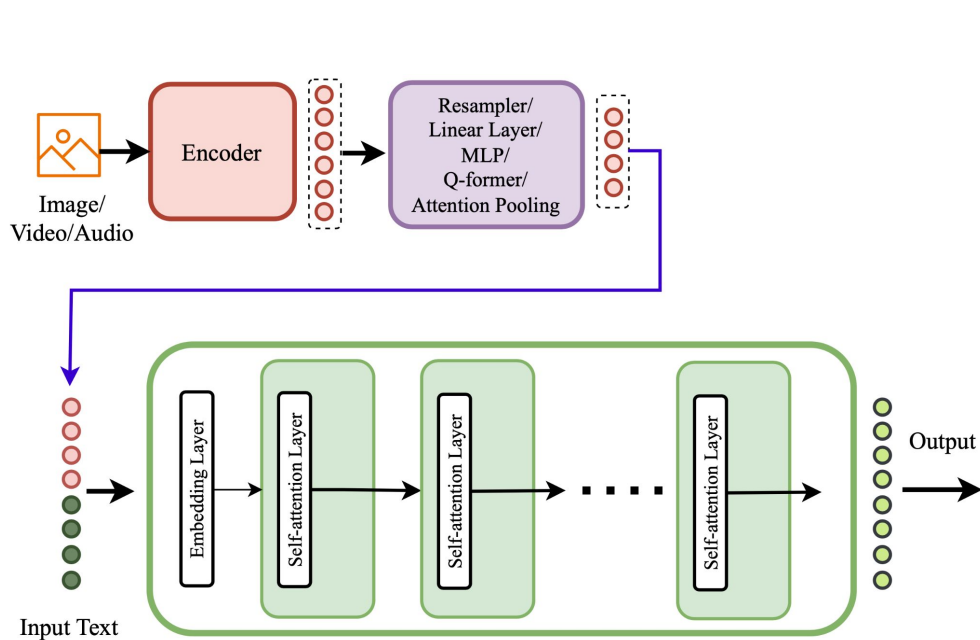
NT-EF: Non-Tokenized

Non-tokenized input modalities are **directly fed to the model** rather than to internal layers



NT-EF: Non-Tokenized

Non-tokenized input modalities are **directly fed to the model** rather than to internal layers



- **Q-Former:** BLIP-2 🏆, MiniGPT-v2
- **Custom layer:** Qwen-VL, AnyMAL, Video-ChatGPT, EmbodiedGPT
- **Linear / MLP:** DeepSeek-VL, LLaVA, LLaVA-NeXT, PaLM-E, Shikra
- **Perceiver resampler:** Monkey, V*, Kosmos-G

NT-EF: **Qwen-VL** (Oct 2023)



Qwen-VL

Alibaba Group, 9.6B parameters

vision model = OpenClip ViT-bigG, **language model** = Qwen-7B

NT-EF: Qwen-VL (Oct 2023)



Qwen-VL

Seminar 2
Early Fusion

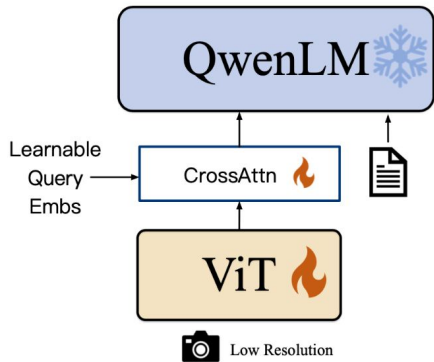
7

Alibaba Group, 9.6B parameters

vision model = OpenClip ViT-bigG, **language model** = Qwen-7B

Stage 1: Pretraining

5B web data pairs \rightarrow 1.4B



NT-EF: Qwen-VL (Oct 2023)

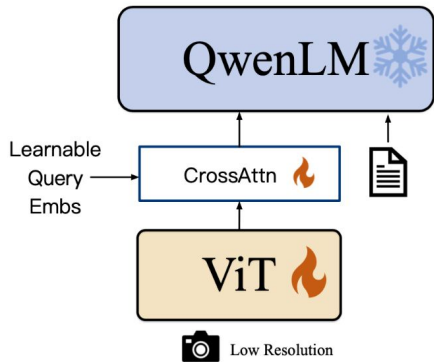


Alibaba Group, 9.6B parameters

vision model = OpenClip ViT-bigG, **language model** = Qwen-7B

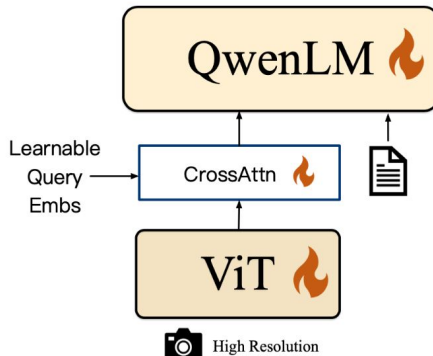
Stage 1: Pretraining

5B web data pairs \rightarrow 1.4B



Stage 2: Multi-task pretraining

high quality, \sim 80M data



NT-EF: Qwen-VL (Oct 2023)

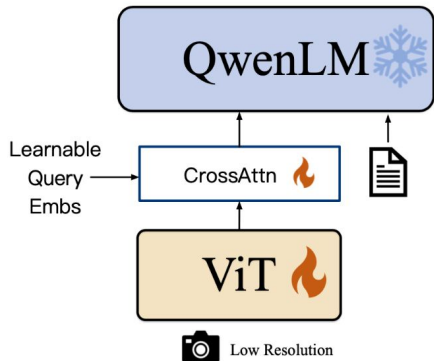


Alibaba Group, 9.6B parameters

vision model = OpenClip ViT-bigG, **language model** = Qwen-7B

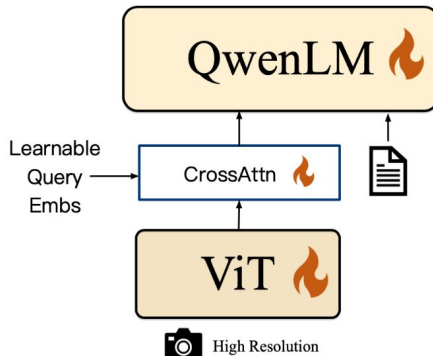
Stage 1: Pretraining

5B web data pairs → 1.4B



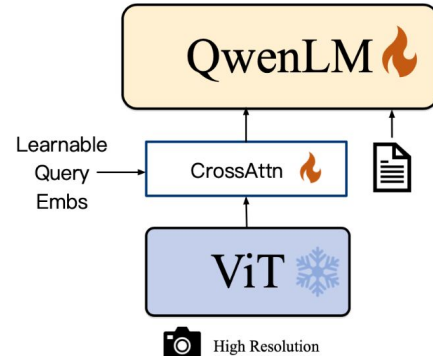
Stage 2: Multi-task pretraining

high quality, ~80M data



Stage 3: Supervised Fine-tuning

instructions, 350k data



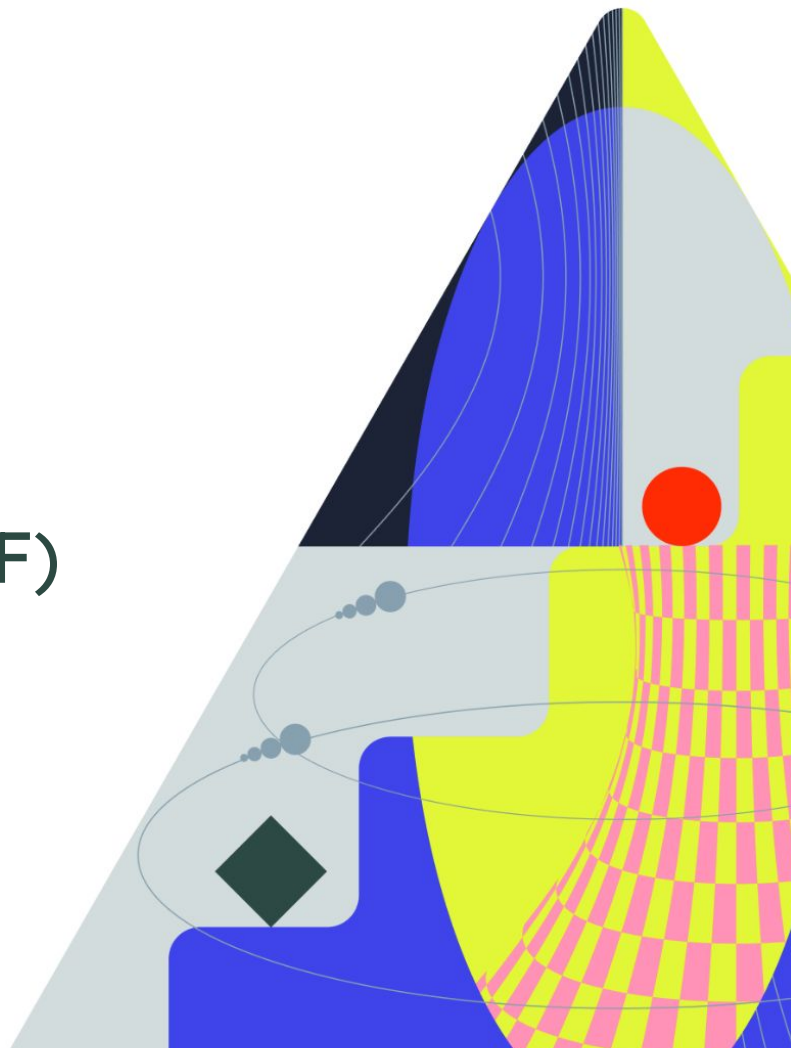
Qwen-VL-Chat



2.2

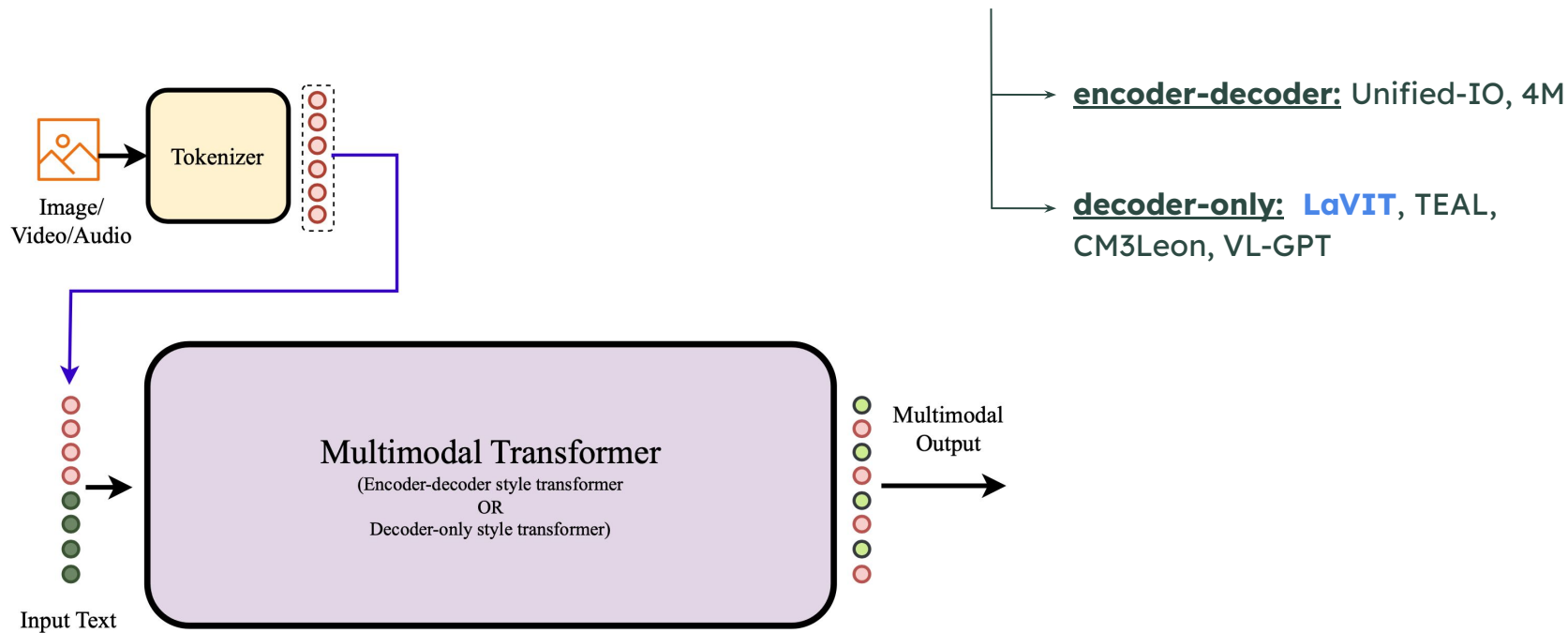
Early Fusion:

Tokenized Early Fusion (T-EF)



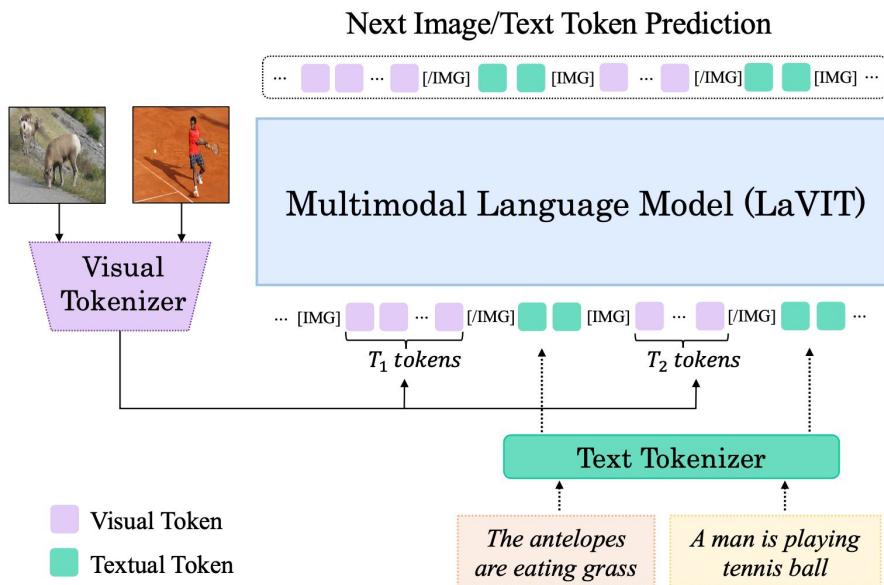
T-EF: Tokenized

Inputs are tokenized **using a common tokenizer** or modality specific tokenizers



T-EF: **LaVIT** (Mar 2024, ICLR)

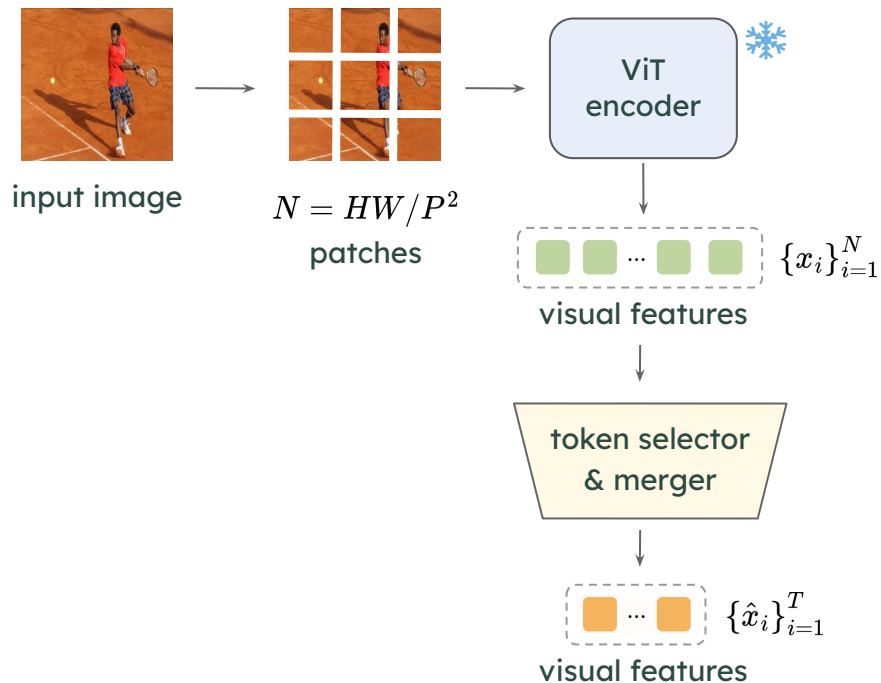
LaVIT — Language-Vision Transformer by researchers from Peking & Kuaishou University



1. represent two modalities in a uniform form to exploit **LLM's next-token prediction**
2. visual tokenizer returns sequence of **discrete visual tokens** possessing word-like high-level semantics

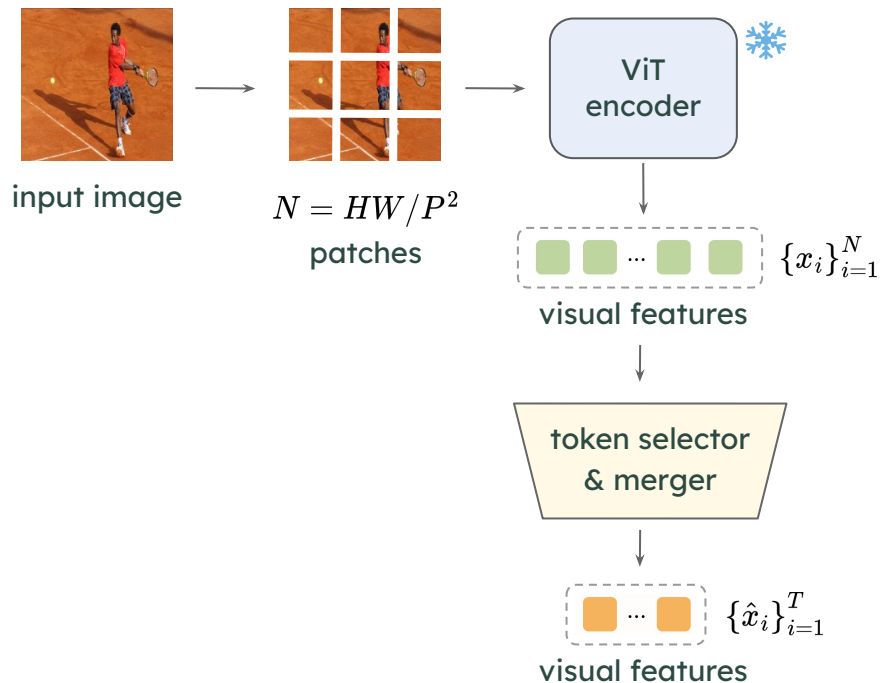
T-EF: **LaViT** (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B

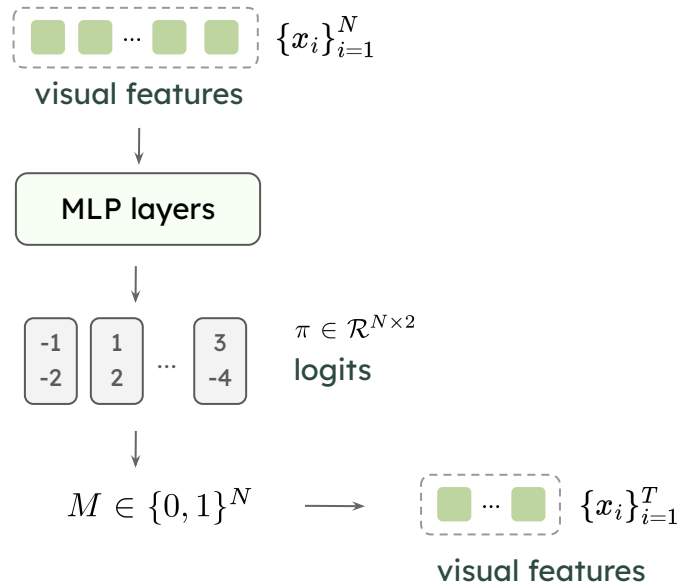


T-EF: LaViT (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B

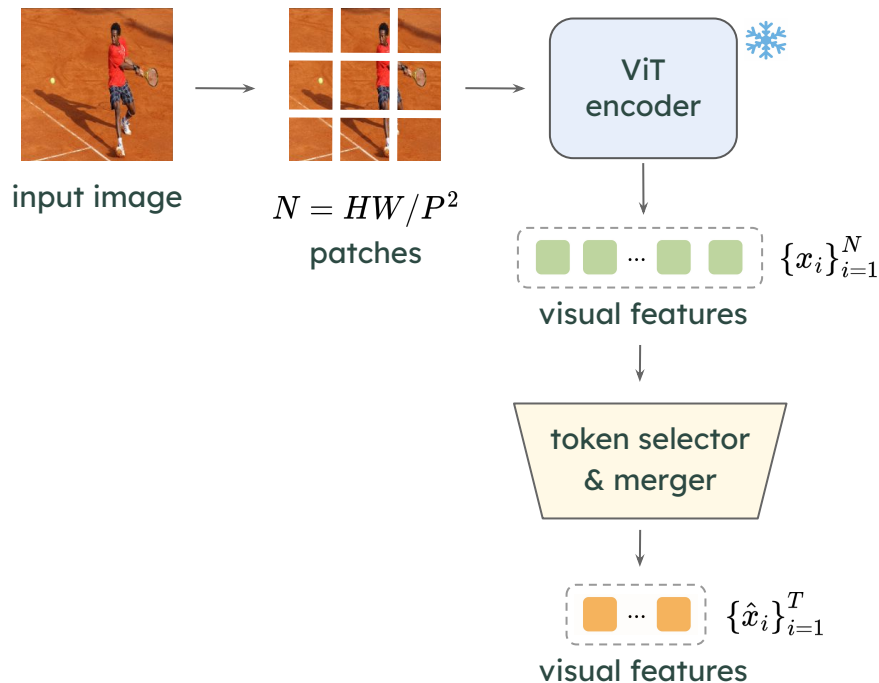


1 token selector

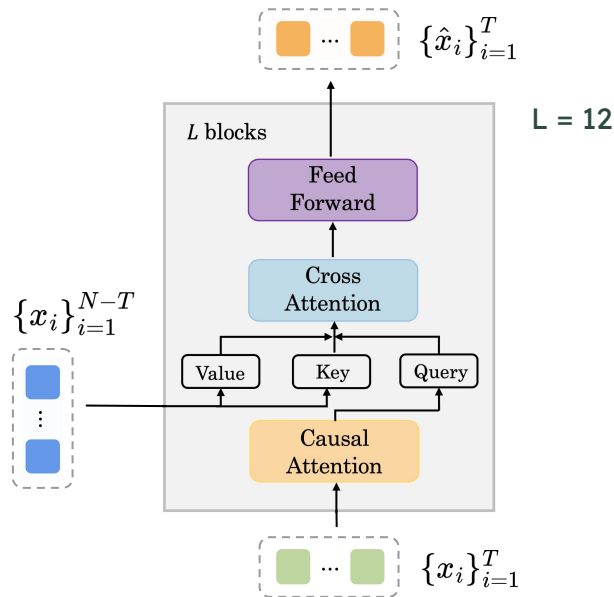


T-EF: LaViT (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B

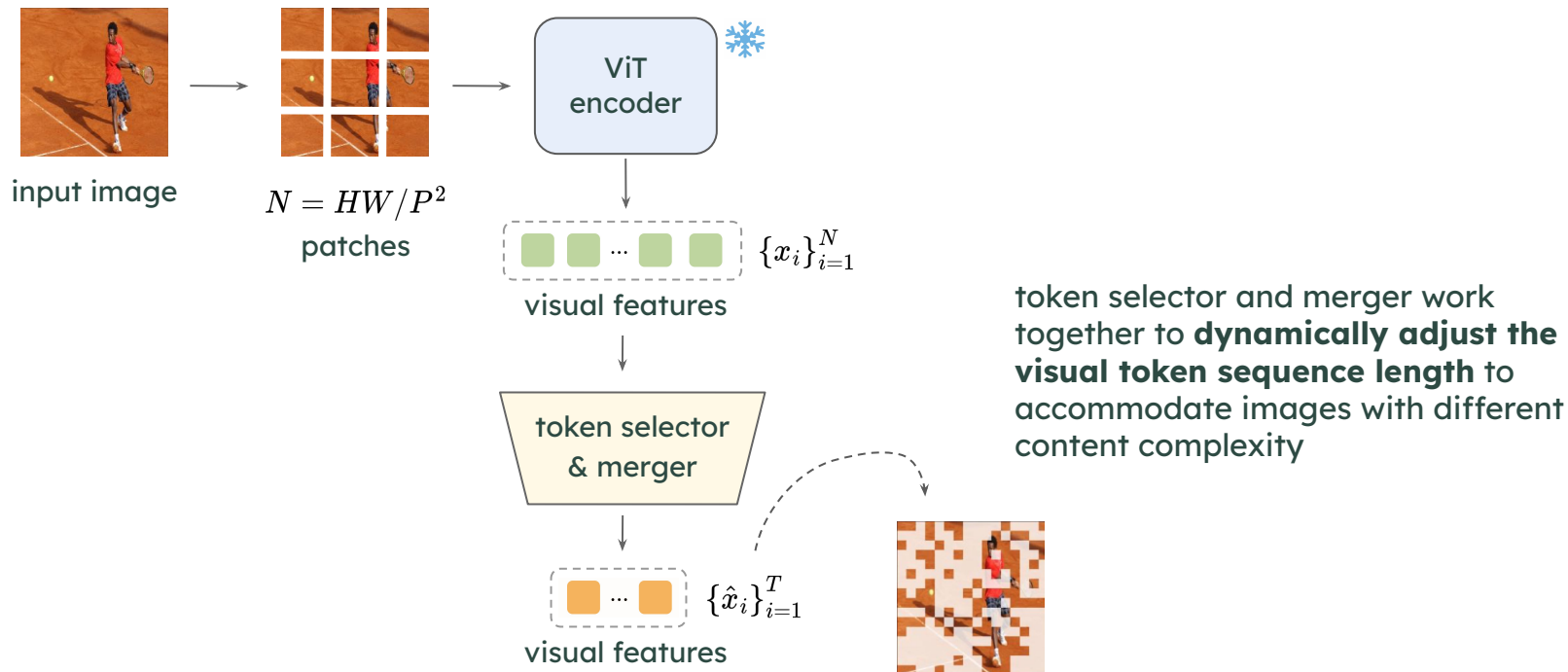


2 token merger



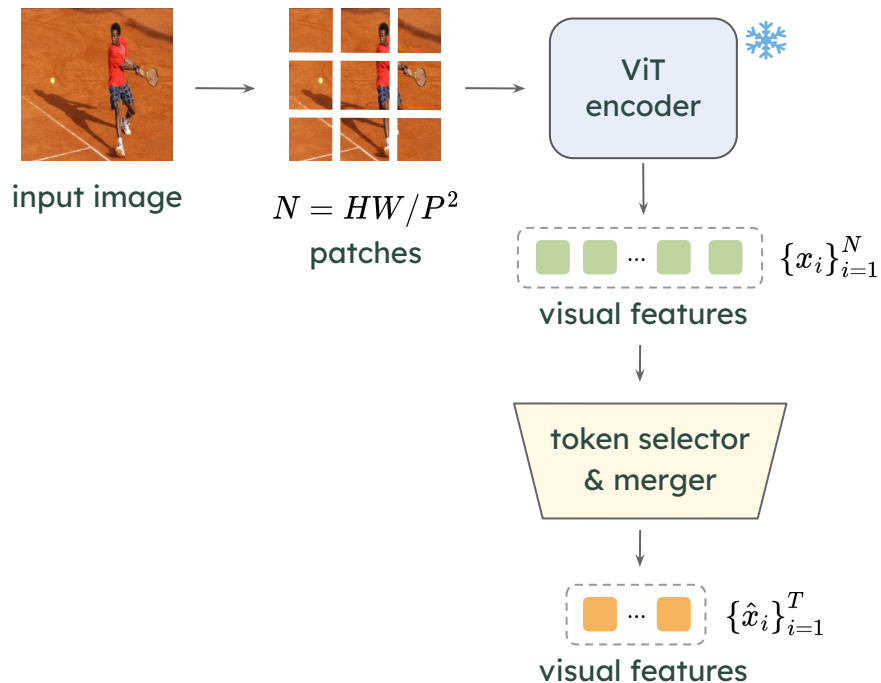
T-EF: LaViT (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B



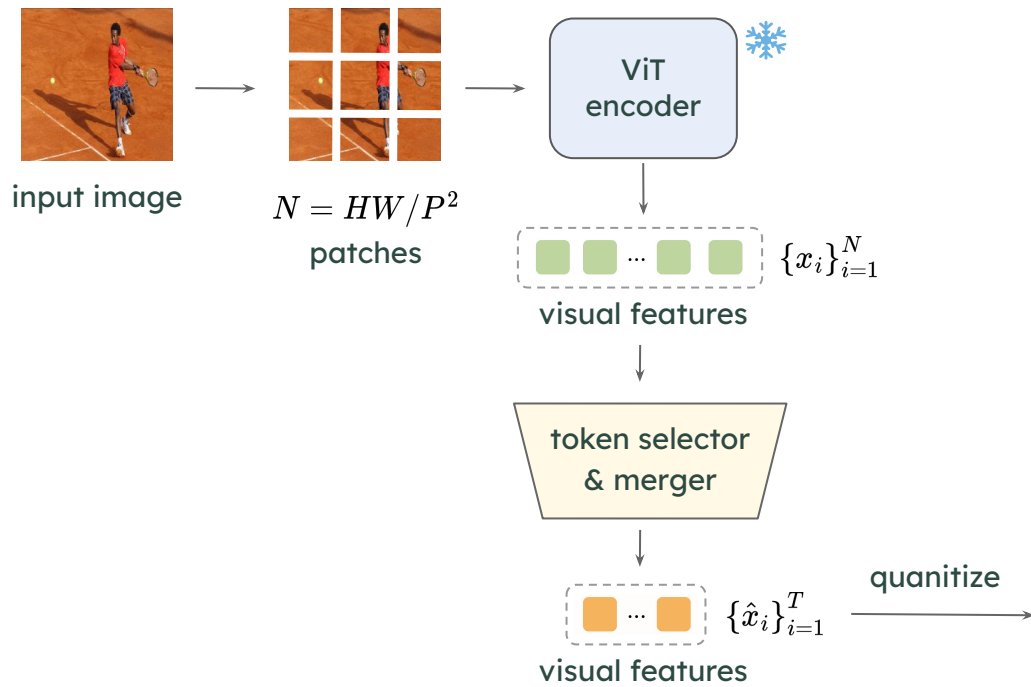
T-EF: **LaViT** (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B

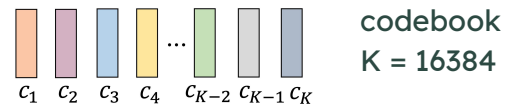


T-EF: LaViT (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B



vector quantization

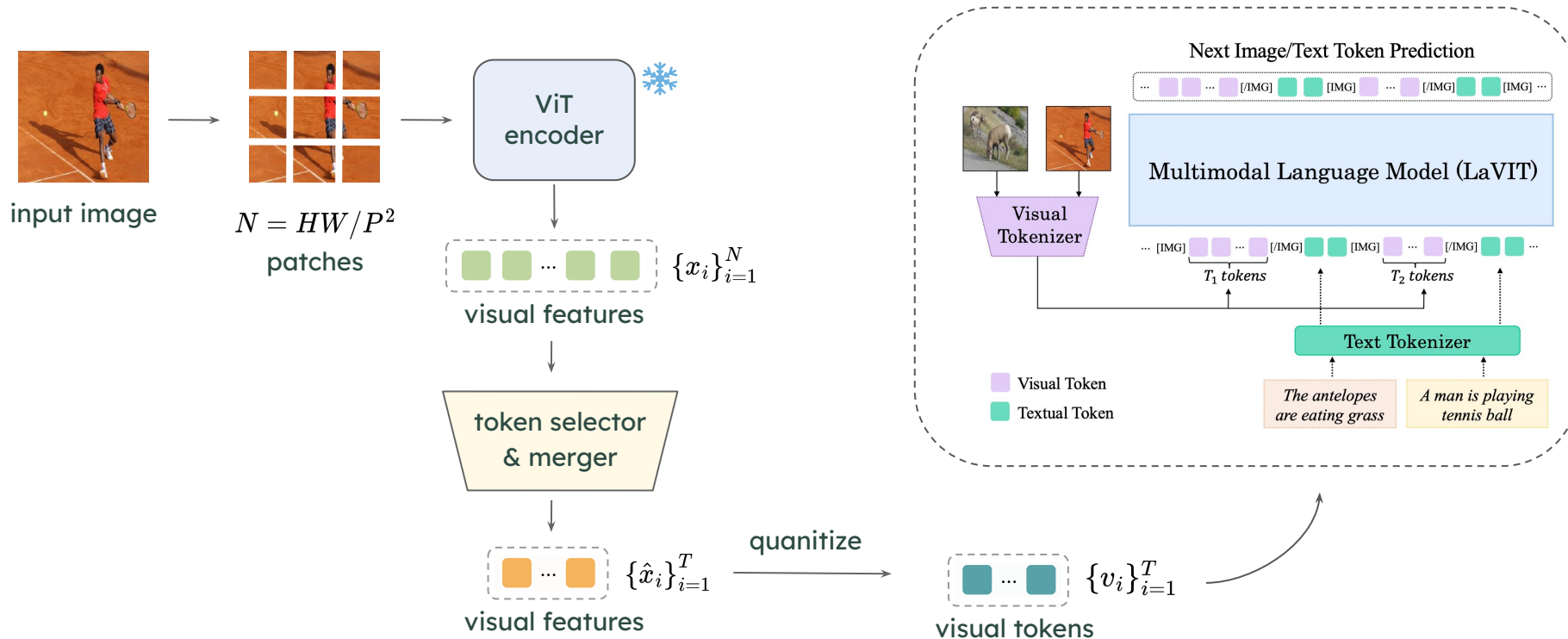


$$v_i = \arg \min_j \|l_2(\hat{x}_i) - l_2(c_j)\|_2$$

$$v_i \in [0, K - 1]$$

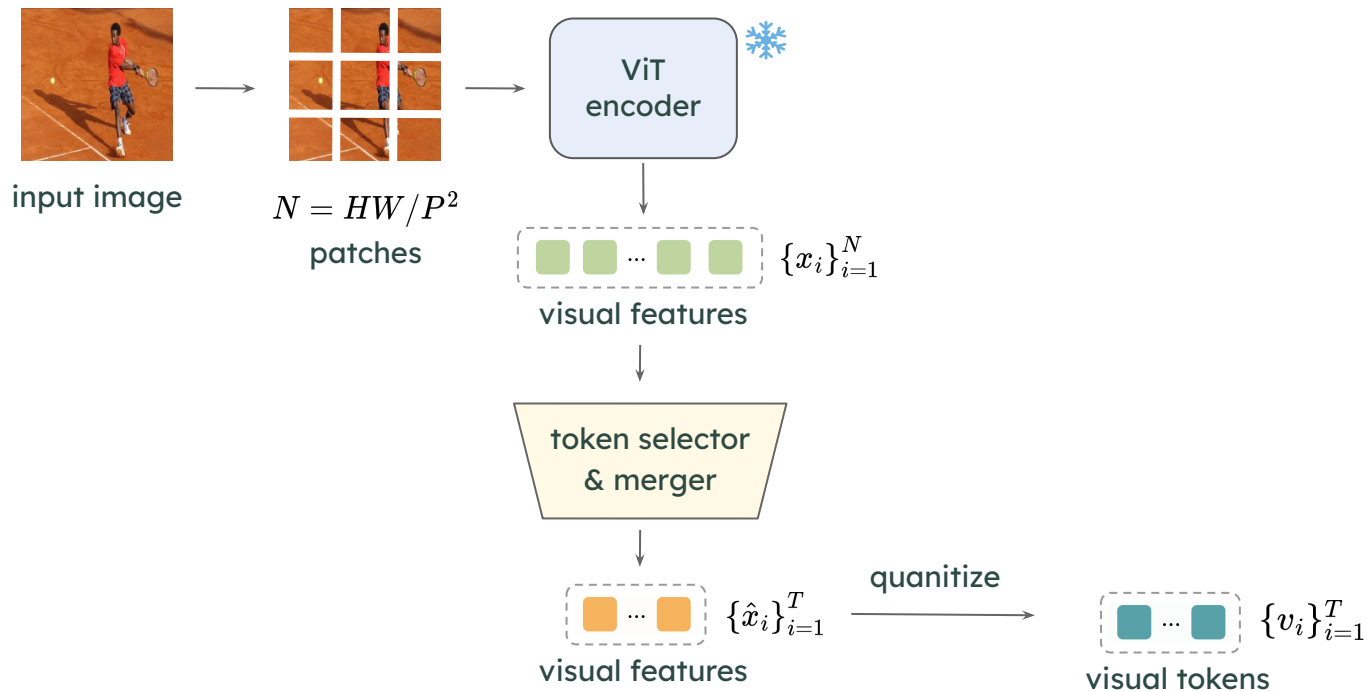
T-EF: LaViT (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B



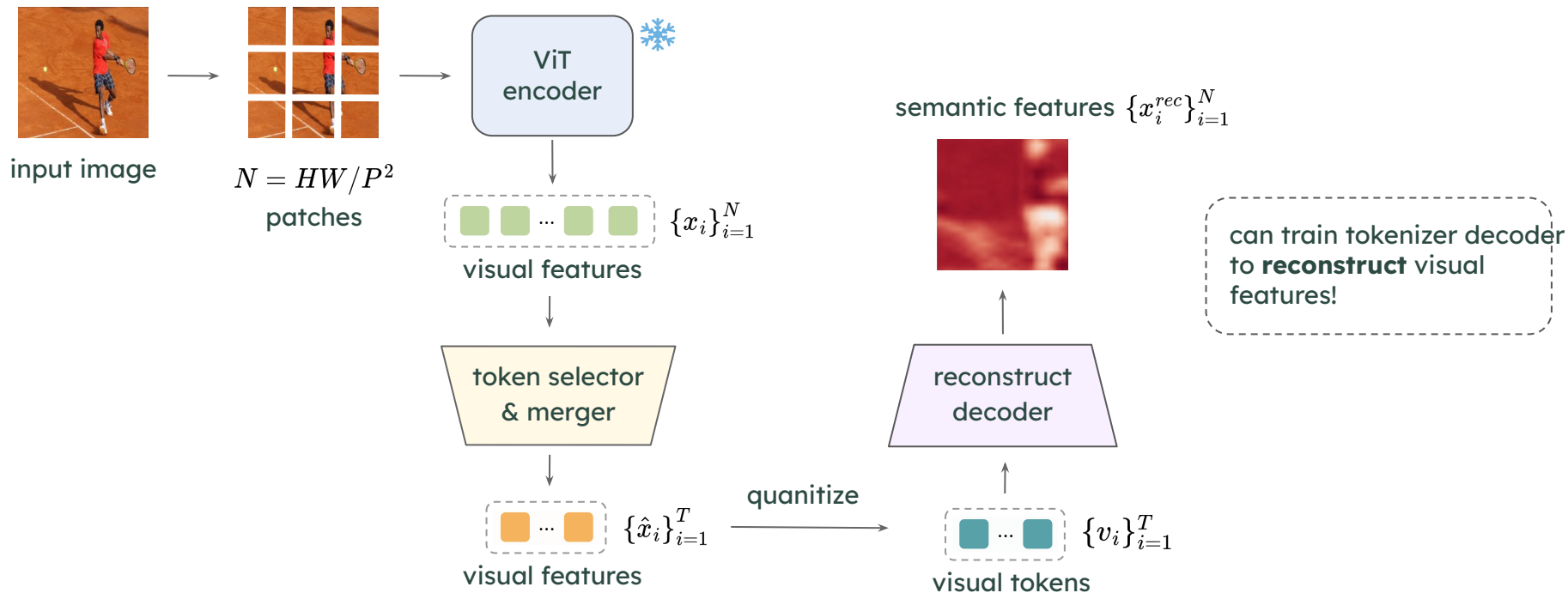
T-EF: **LaViT** (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B



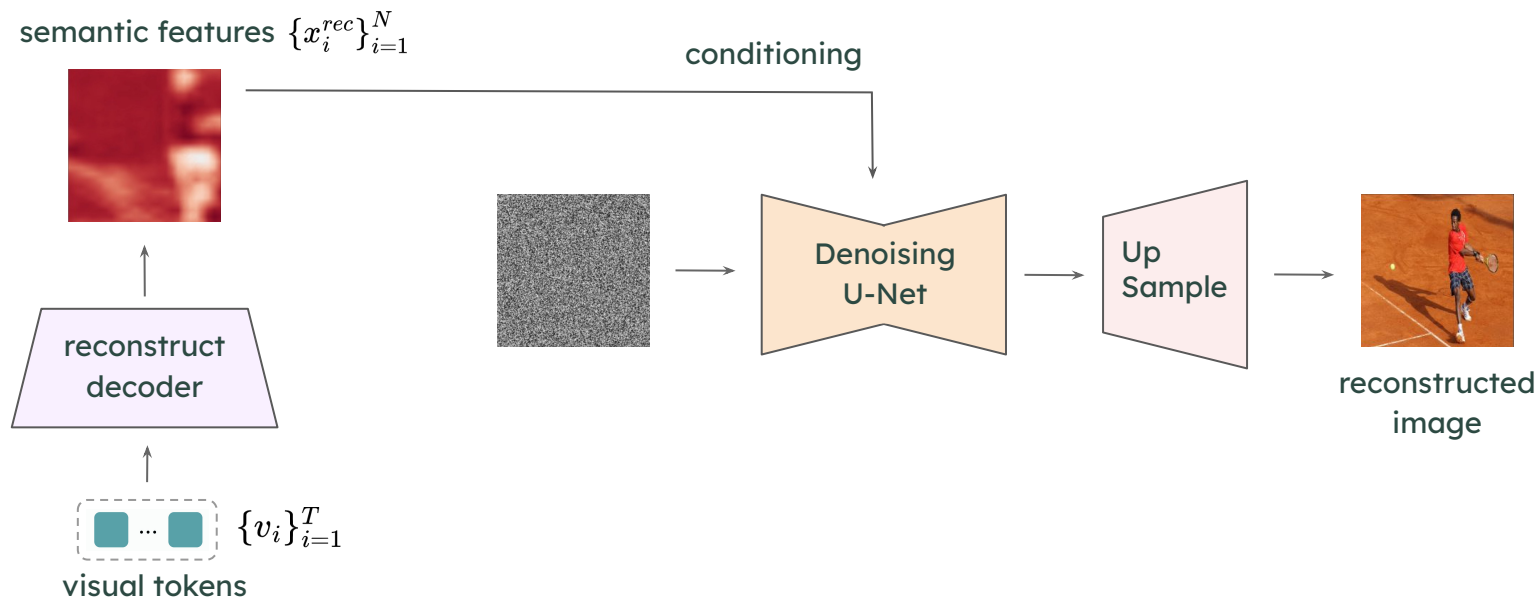
T-EF: LaViT (Mar 2024, ICLR)

vision model = ViT-G/14 of EVA-CLIP, **language model** = LLaMA-7B



T-EF: LaVIT (Mar 2024, ICLR)

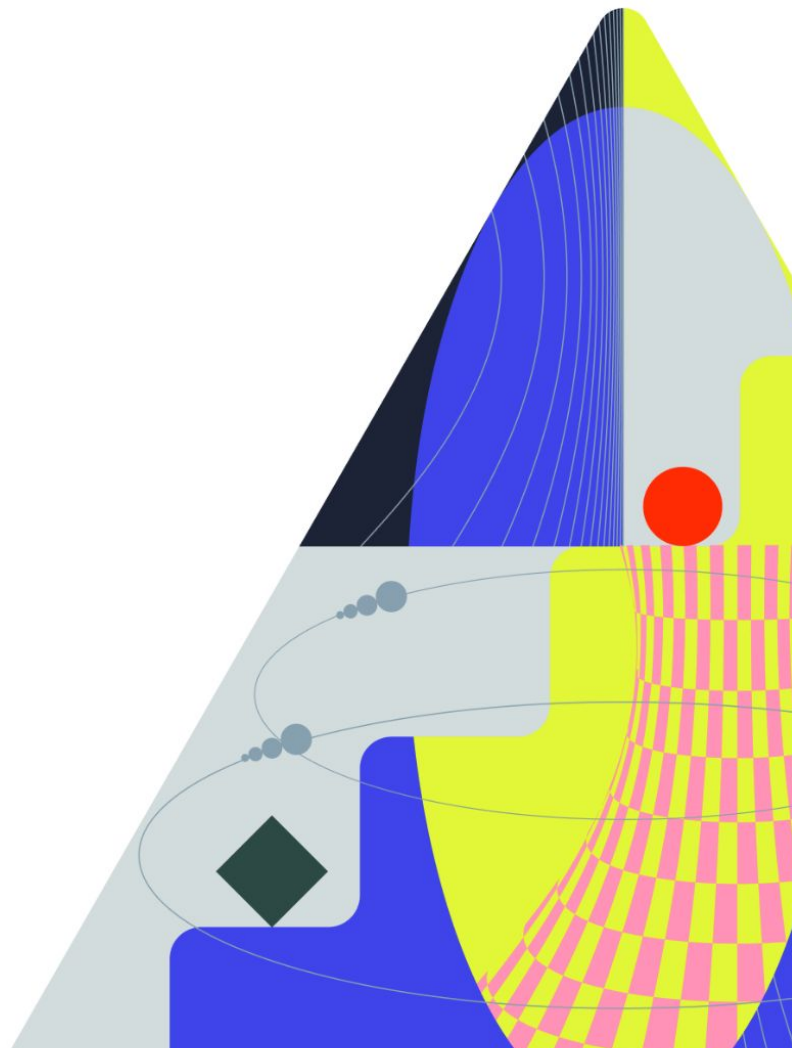
During inference, the generated visual tokens from LaVIT **can be decoded** into realistic images **by this U-Net!**



Part 2

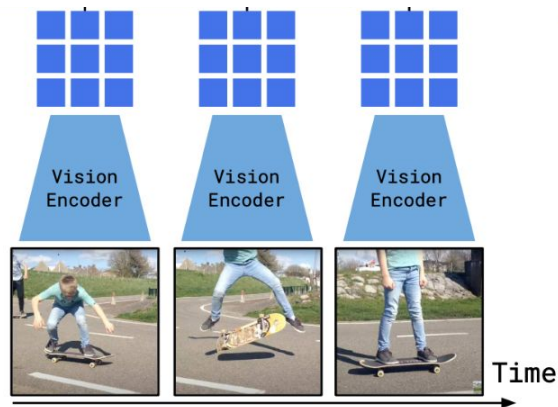
Video Modality

Examples of such models

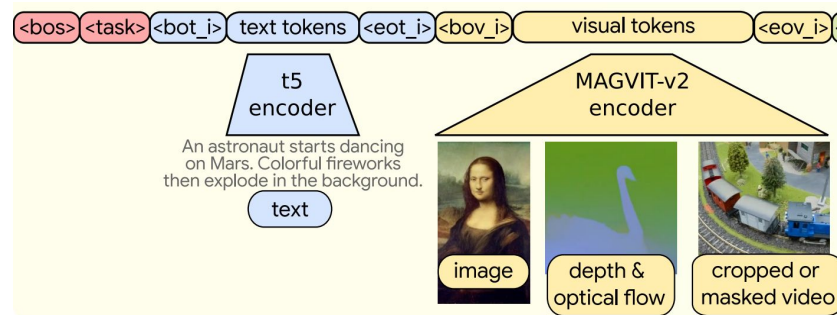


General Approaches

1 uniformly downsample the original video into a **series of frames**



2 uniformly downsample the original video into a **series of frames**

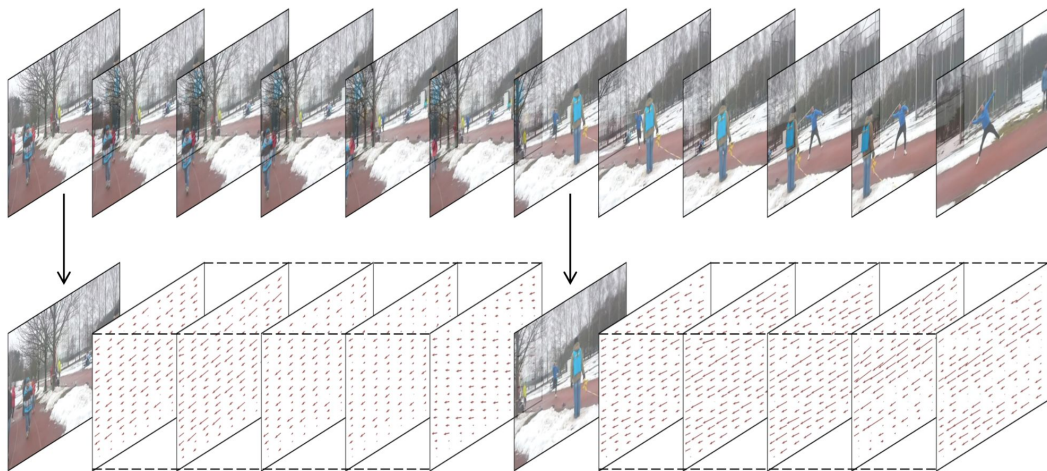


[1] **Flamingo**: a Visual Language Model for Few-Shot Learning. Apr 2022. [\[link\]](#)

[2] **VideoPoet**: A Large Language Model for Zero-Shot Video Generation. Jun 2024. [\[link\]](#)

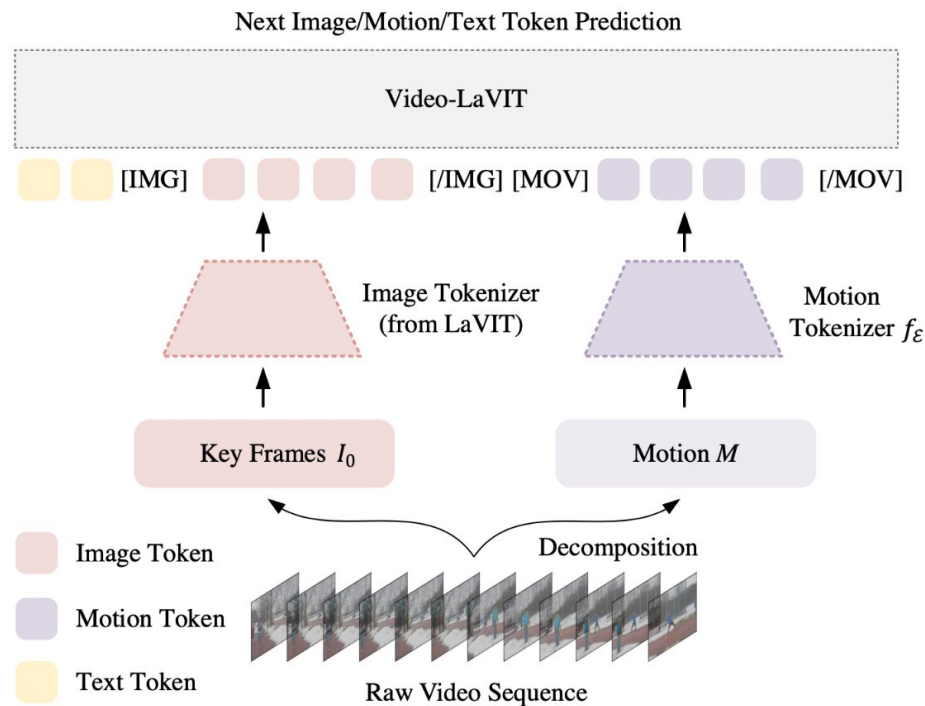
VideoLaVIT (Feb 2024) – ICML 2025

Key observation: most video parts have a high degree of temporal redundancy that may be described by **motion vectors**



most video frames are not needed and can be described by **motion vectors**, decreasing the number of utilized visual tokens

VideoLaVIT (Feb 2024) – ICML 2025

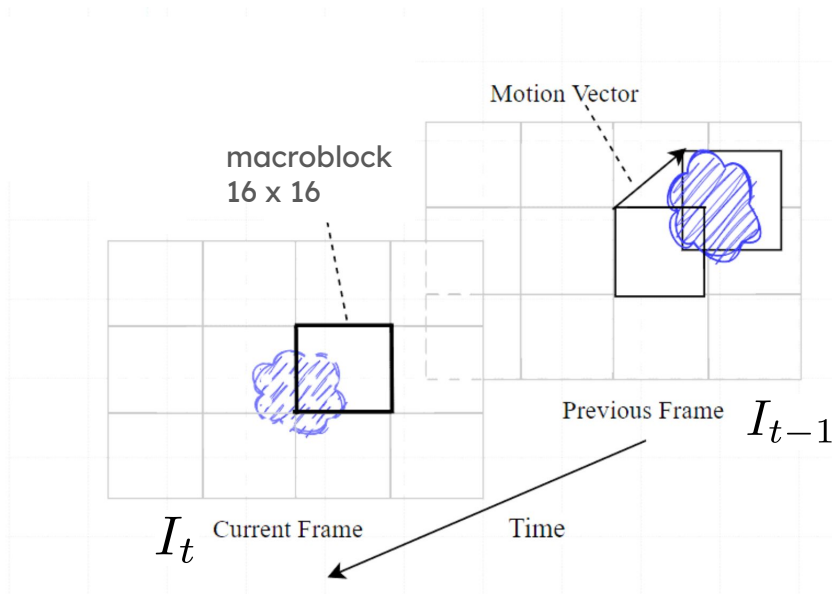


- introduce **novel video-tokenizer** and **video-detokenizer** to adapt visual features to LLM
- video tokens can be updated through the same **next-token-prediction** objective

VideoLaVIT (Feb 2024) – ICML

2025

Employ the **MPEG-4** (1991) to divide the image to **keyframes** (primary semantics) and **motion** (temporal evolution)

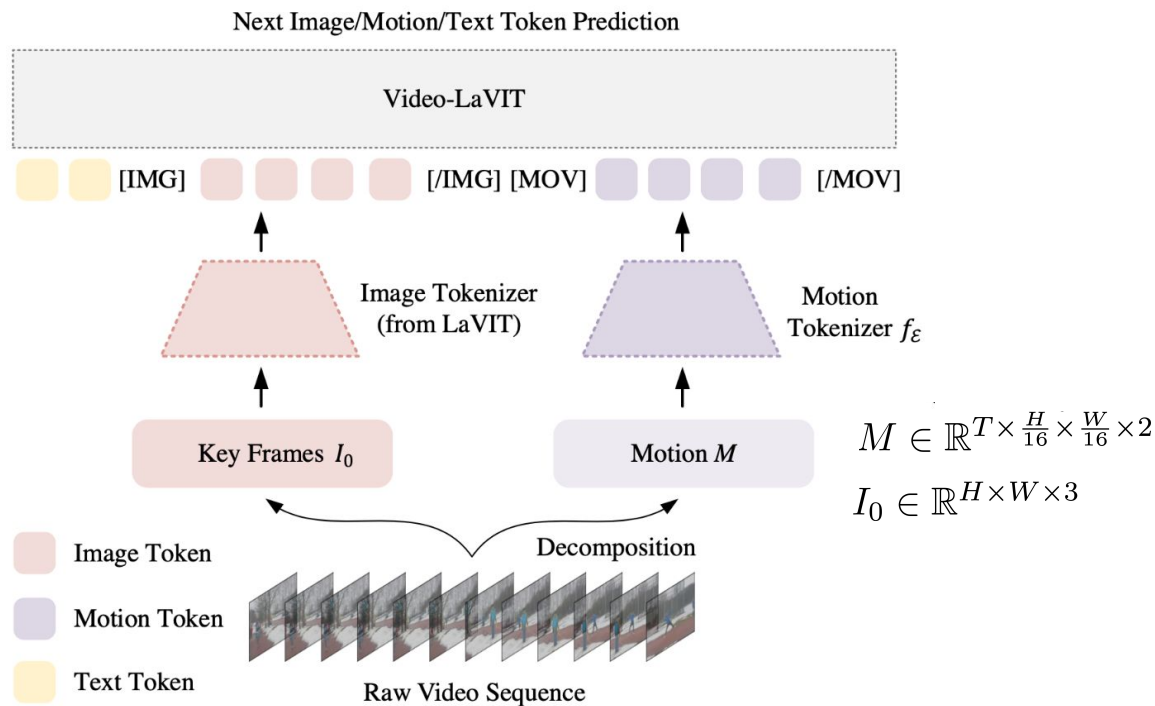


$$\vec{m}(p, q) = \arg \min_{i, j} \|I_t(p, q) - I_{t-1}(p - i, q - j)\|$$

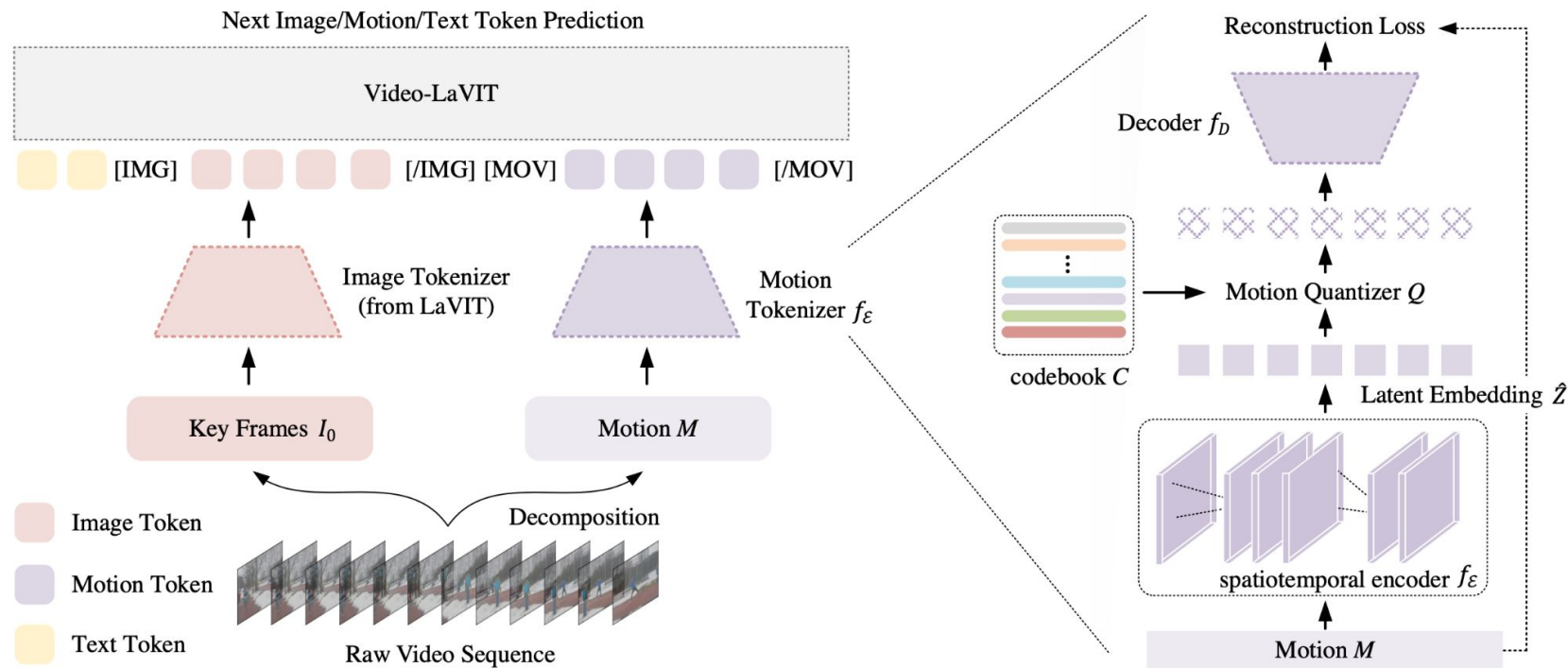
(i, j) – coordinate offset between the center of 2 macroblocks

$$\begin{aligned} \text{video clip} &\longrightarrow I_0 \in \mathbb{R}^{H \times W \times 3} \\ &M \in \mathbb{R}^{T \times \frac{H}{16} \times \frac{W}{16} \times 2} \end{aligned}$$

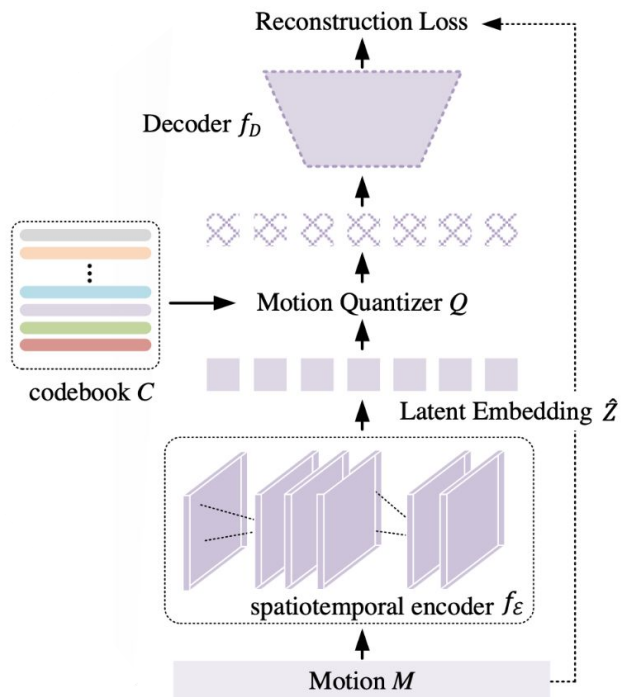
VideoLaVIT (Feb 2024) – ICML 2025



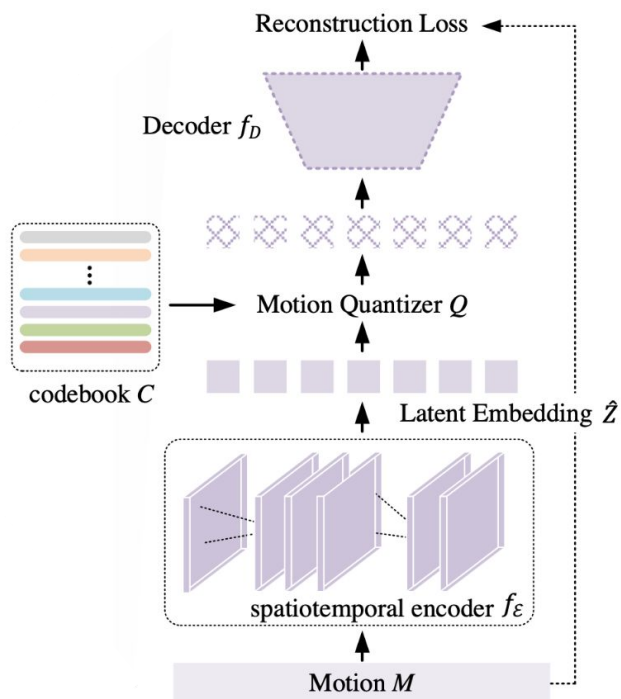
VideoLaVIT (Feb 2024) – ICML 2025



VideoLaVIT (Feb 2024) – ICML 2025



VideoLaVIT (Feb 2024) – ICML 2025



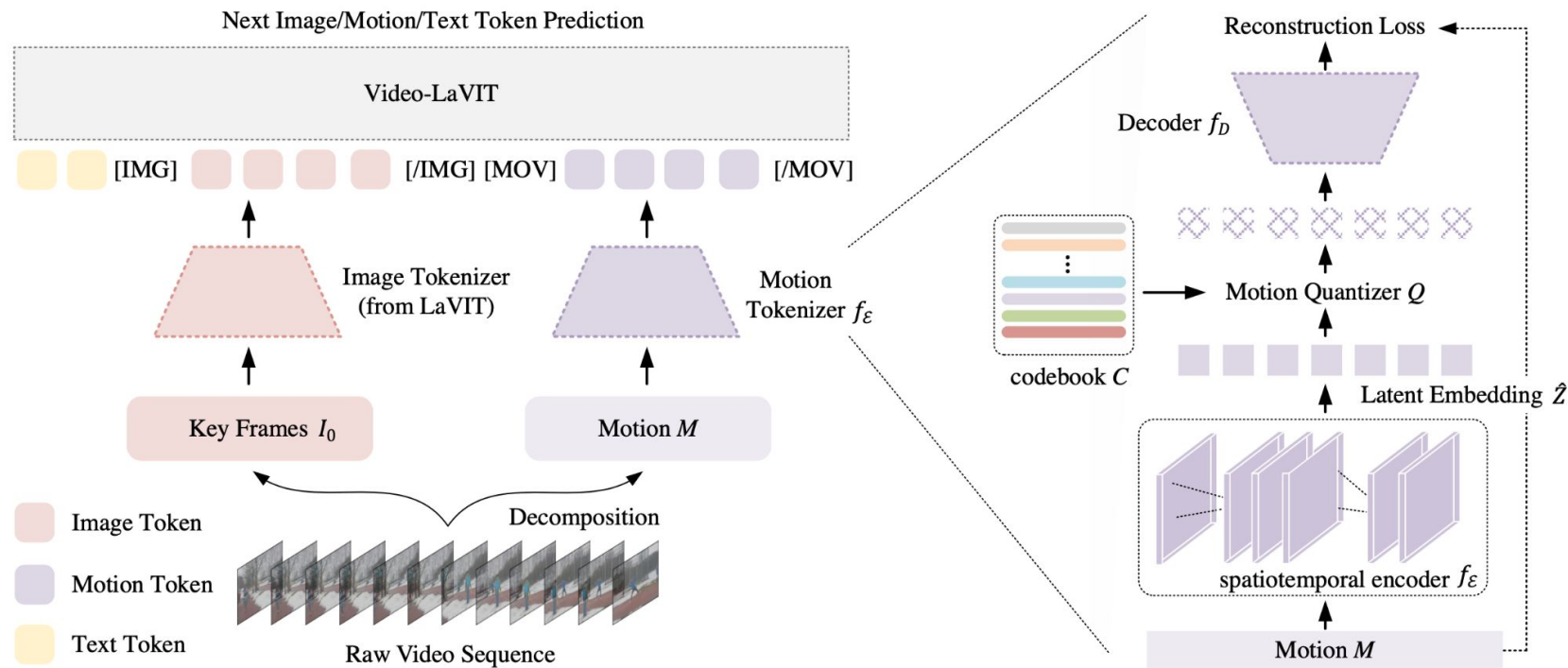
Each embedding vector is then tokenized by a vector quantizer

$$z_i = \arg \min_j \|l_2(\hat{z}_i) - l_2(c_j)\|_2$$

$$\hat{Z} \in \mathbb{R}^{N \times d}$$

$$M \in \mathbb{R}^{T \times \frac{H}{16} \times \frac{W}{16} \times 2}$$

VideoLaVIT (Feb 2024) – ICML 2025



Conclusions

- 1 Considered **classification of VLMs** based on feature fusion
- 2 Investigated models for **Deep Fusion**: OpenFlamingo, MoE-LLaVA
- 3 Investigated models for **Early Fusion**: Qwen-VL, LaVIT
- 4 Explored **Video-LaVIT** that processes video modality